## (9) CLAIMS

## What is claimed is:

- 1. A method for cycling trigger-event operations
- of a networked computer peripheral, the method comprising:
- 3 periodically monitoring at least one current
- 4 timestamp service across a network connection;
- 5 recording a first timestamp indicative of
- 6 time of current trigger-event;
- using the first timestamp and current
- 8 timestamp, calculating elapsed time since a last trigger-
- 9 event; and
- re-running said trigger-event operations only
- 11 when the elapsed time exceeds a pre-specified period for
- 12 cycling operations.
- 1 2. The method as set forth in claim 1, said
- 2 calculating further comprising:
- including accounting for any peripheral
- 4 power-off time period.
- 1 3. The method as set forth in claim 1, said
- 2 periodically monitoring further comprising:
- 3 monitoring coordinated universal time from a
- 4 network time protocol server.

- 1 4. The method as set forth in claim 2,
- 2 comprising:
- when no power-off condition occurs during
- 4 operation of the peripheral, calculating elapsed time, ET,
- 5 since a previous trigger-event operation in accordance with
- 6 an equation:
- $7 ET = CT_R TOTE,$
- $\,$  where  $\text{CT}_{\text{R}}$  is the current real time and TOTE is a recorded
- 9 timestamp indicative of the trigger-event, and a
- 10 determination:
- is  $ET > P_{MAX}$  ?,
- where " $P_{MAX}$ " is a maximum period of operation pre-specified
- 13 before re- is to be run.
- 5. The method as set forth in claim 2,
- 2 comprising:
- when a power off condition occurs during
- 4 operation of the peripheral, calculating elapsed time since
- 5 a previous trigger-event operation in accordance with an
- 6 equation:
- 7 ET = RT TOS,
- 8 where TOS is the approximate time of power off condition,
- 9 and
- 10 RT is a timestamp indicative of a following power on
- 11 condition, and a determination:
- is  $ET > P_{MAX}$ ?.

- 1 6. A computer peripheral comprising:
- a machine having a memory including a
- 3 predetermined cyclical machine associated recalibration
- 4 routine; and
- on-board said machine, a network interface
- 6 coupling the machine to a network, an application for
- 7 obtaining timestamps across said interface, and a routine
- 8 for calculating elapsed time since running the predetermined
- 9 cyclical recalibration routine using said timestamps.
- The apparatus as set forth in claim 6 wherein
- 2 said calculating includes accounting for time lapsed while
- 3 said machine is in a power off condition.
- 1 8. The apparatus as set forth in claim in a
- 2 computer peripheral printer.
- 9. A computer memory having code for cycling
- 2 calibration operations of a networked computer peripheral,
- 3 the memory comprising:
- 4 computer code periodically monitoring at
- 5 least one current timestamp service across a network
- 6 connection;
- 7 computer code recording a first timestamp
- 8 indicative of time of current calibration operation;
- 9 using the first timestamp and current

- 10 timestamp, computer code calculating elapsed time since a
- 11 last trigger-event cycle; and
- 12 computer code re-running said calibration
- operations only when the elapsed time exceeds a pre-
- 14 specified period for cycling operations.
- 1 10. The memory as set forth in claim 9, said
- 2 computer code calculating further comprising:
- including accounting for any peripheral
- 4 power-off time period.
- 1 11. The memory as set forth in claim 9, said
- 2 computer code periodically monitoring further comprising:
- monitoring coordinated universal time from a
- network time protocol server.
- 1 12. The memory as set forth in claim 10,
- 2 comprising:
- when no power-off condition occurs during
- 4 operation of the peripheral, computer code calculating
- 5 elapsed time, ET, since a previous calibration operation in
- 6 accordance with an equation:
- $ET = CT_R TOTE,$
- 8 where  $\mathrm{CT}_{\scriptscriptstyle R}$  is the current real time and TOTE is a recorded
- 9 timestamp indicative of the trigger-event, and a
- 10 determination:

- is  $ET > P_{MAX}$ ?,
- where "P<sub>MAX</sub>" is a maximum period of operation pre-specified
- 13 before recalibration is to be run.
- 1 13. The memory as set forth in claim 10,
- 2 comprising:
- when a power off condition occurs during
- 4 operation of the peripheral, computer code calculating
- 5 elapsed time since a previous calibration operation in
- 6 accordance with the equations:
- 7 ET = RT TOS,
- where TOS is the approximate time of power off condition,
- 9 RT is a timestamp indicative of a following power on
- 10 condition, and
- is ET >  $P_{MAX}$  ?.
  - 1 14. The memory as set forth in claim 9, the code
  - 2 for cycling calibration operations of a networked computer
  - 3 peripheral comprising:
  - a Java application on a Java Virtual Machine.